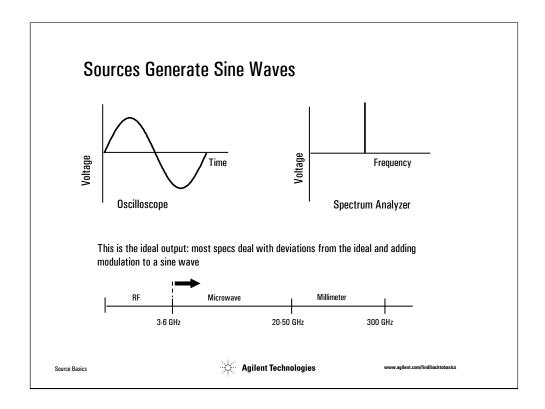
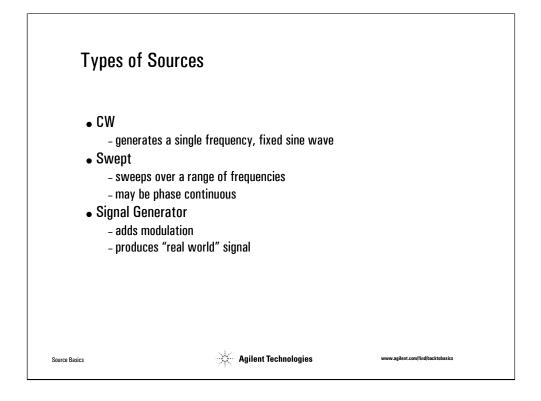


A signal source produces sine waves. This is the most basic definition of a signal source.

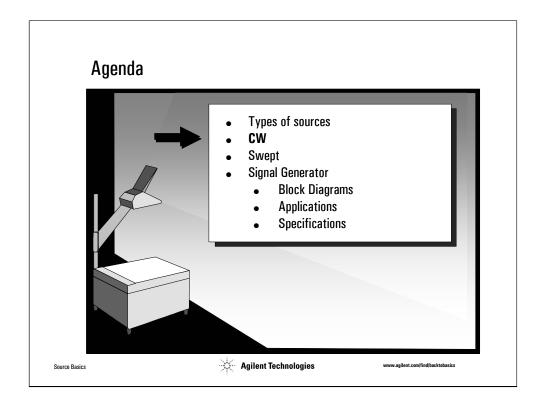
In this seminar, three types of sources will be reviewed. Block diagrams will be used to explain how sources work. For each type of source, several applications will be reviewed and the critical specifications for each application will be emphasized.

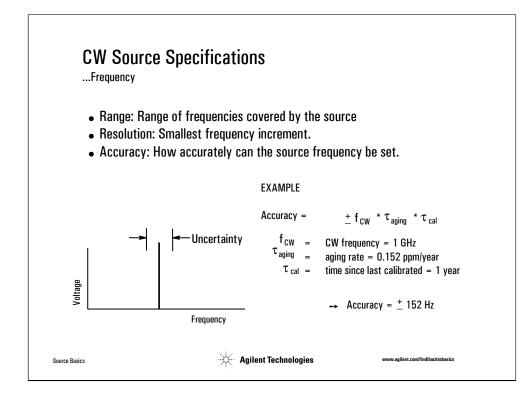


The specifications associated with spectral purity are often the most difficult to understand. The ideal CW output is a sine wave at a single frequency. Unfortunately, their are no ideal CW sources: All sources are made with non-ideal (i.e. real) components. These components introduce phase noise and unwanted distortion products.



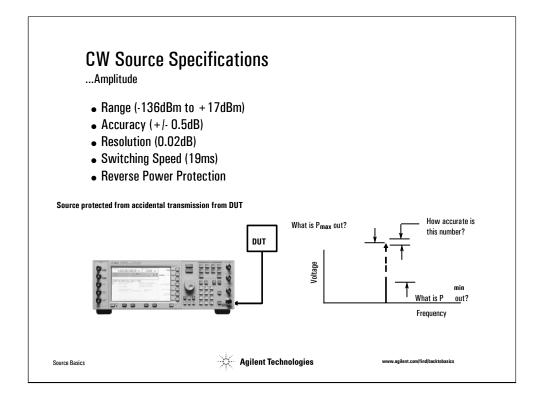
In the ideal case, all of the power in a sine wave is concentrated at a single frequency. Random noise within the source will cause the power to be spread over a small range of frequencies. The spread is referred to as phase noise and is often mathematically modeled as random phase modulation. The units of phase noise are dBc/Hz: dB down from the carrier in a 1 Hz bandwidth. Phase noise is specified at a frequency offset from the CW output. For example, the phase noise of a CW source may be specified as: -97dBc/Hz @ 100 kHz offset from a CW frequency at 20 GHz.





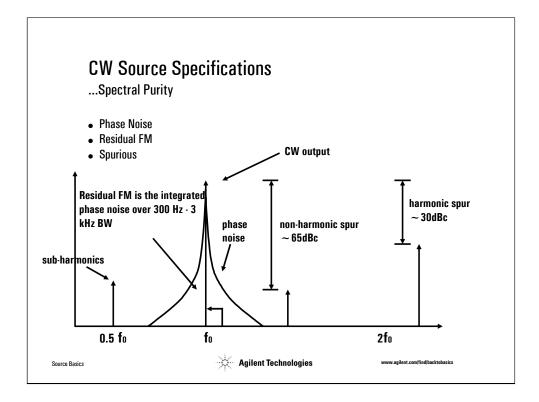
Understanding source specifications is critical when determining the appropriate source for an application. For CW sources, the specifications are generally divided into three broad categories: Frequency, amplitude (or output), and spectral purity.

Range, resolution, and accuracy are the main frequency specifications. Range specifies the range of output frequencies that the source can produce. Resolution is the smallest frequency increment. The accuracy of a source is affected by two parameters: The stability of the reference oscillator and the amount of time that has passed since the source was last calibrated. A typical (but very good) reference oscillator may have an aging rate of 0.152ppm (parts-per-million) per year. The aging rate indicates how far the reference will drift (either up or down) from its specified value. At 1 GHz, a source that has not been calibrated for one year with an aging rate of 0.152ppm per year will be within 152 Hz of its specified output frequency.



Range, accuracy, resolution, switching speed, and reverse power protection are the main amplitude specifications. The range of a source is determined by the maximum output power and the amount of internal attenuation built into the source. Sources monitor their own output power to maintain amplitude accuracy. Automatic leveling circuits are used to measure the output. The resolution of a source indicates the smallest amplitude increment. Switching speed is a measure of how fast the source can change from one amplitude level to another.

Sources are often used to test transceivers. Because transceivers have transmitters, the connection between a source and the transceiver could conduct a signal from the device being tested to the output connector of the source. Reverse power protection prevents signals traveling the wrong direction from damaging the source.



The specifications associated with spectral purity are often the most difficult to understand. The ideal CW output is a sine wave at a single frequency. Unfortunately, their are no ideal CW sources: All sources are made with non-ideal (i.e. real) components. These components introduce phase noise and unwanted distortion products.

Harmonic spurs are integer multiples of the CW output. Sources contain many non-linear components. These components are needed to provide a broad range of frequencies and output powers. Consider the output of an amplifier:

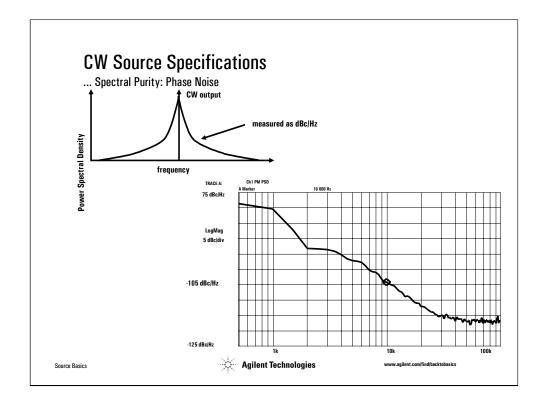
$$v_{0}(t) = a_{1} v_{i}(t) + a_{2} v_{i}^{2}(t) + a_{3} v_{i}^{3}(t) + \dots$$

For an input sine wave, the output is:

 $v_0(t) = a_1 \sin(\omega t) + a_2 \sin^2(\omega t) + a_3 \sin^3(\omega t) + \dots$ = $a_2/2 + a_1 \sin(\omega t) + 3a_3/4 \sin(\omega t) + a_2/2 \sin(2\omega t) + a_3/4 \sin(3\omega t) + \dots$

The non-linear characteristics of an amplifier create second, third, and higher order harmonics. A typical second harmonic will be specified at < -30 dBc (better than 30 dB below the output of the fundamental frequency). Non-harmonic spurs come from a variety of sources (e.g. power supply) and are typically quite low (< -65 dBc).

Multipliers are often used in sources to extend the frequency output. This results in the presence of subharmonics.

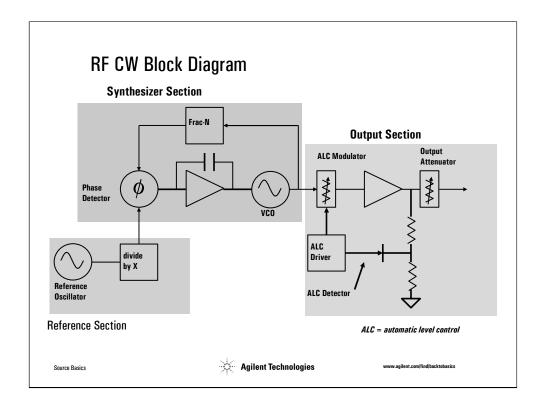


In the ideal case, all of the power in a sine wave is concentrated at a single frequency. Random noise within the source will cause the power to be spread over a small range of frequencies. The spread is referred to as phase noise and is often mathematically modeled as random phase modulation. The units of phase noise are dBc/Hz: dB down from the carrier in a 1 Hz bandwidth. Phase noise is specified at a frequency offset from the CW output. For example, the phase noise of a CW source may be specified as: -97dBc/Hz @ 100 kHz offset from a CW frequency at 20 GHz.

Phase noise may be directly measured from the spectrum of a source. This method requires that the phase noise of the analyzer be much better (~ 10 dB) than the phase noise of the source being tested. Often, the phase noise of a source is measured using test equipment that has been optimized for this purpose. Phase noise is generally displayed on a log-log axis. This enables both the close in phase noise (offsets < 1 kHz) and the far out phase noise (offsets > 10 kHz) to be easily examined on one plot.

The phase noise plot above was generated using the Agilent 89441A by displaying the power spectral density (units of dBm/Hz) of a phase demodulated signal. The source is at 1 GHz. The marker is at a 10 kHz offset and reads -104dBc/Hz.

Residual FM is a measure of the small amount of FM inherent in an CW output. Residual FM is specificied within a bandwidth. Most sources typically specify residual FM per the CCITT specified bandwidth. The CCITT bandwidth starts at 300 Hz offset from the carrier frequency and stops at a 3 kHz offset. Within this band, all of the noise shown on the phase noise curve contributes to residual FM. ..



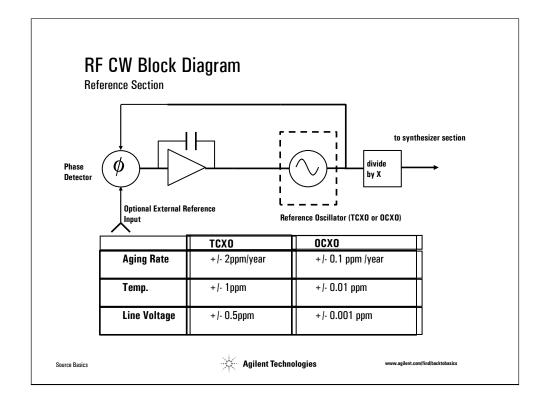
The above block diagram provides greater detail for an RF CW source.

The reference section supplies the reference oscillator for the source. The reference oscillator contributes to the short term stability of the output frequency (phase noise). The long term stability of the reference oscillator, the aging rate, determines the accuracy of the output frequency.

The reference section supplies a sine wave with a known frequency to the synthesizer section. This sine wave is used as the reference for a phase-locked loop (PLL). The synthesizer section is responsible for producing a clean sine wave at the desired frequency. The VCO (voltage controlled oscillator) produces the sine wave. The PLL maintains the output frequency at the desired setting and translates the frequency accuracy of the reference oscillator to the output of the VCO.

The synthesizer section supplies a clean sine wave to the output section. The output section determines the overall amplitude range and accuracy of the source. Amplitude range is determined by the available amplification and attenuation. Amplitude accuracy, or level accuracy, is maintained by monitoring the output power and adjusting the power as needed.

Let's take a look at each section in more detail.

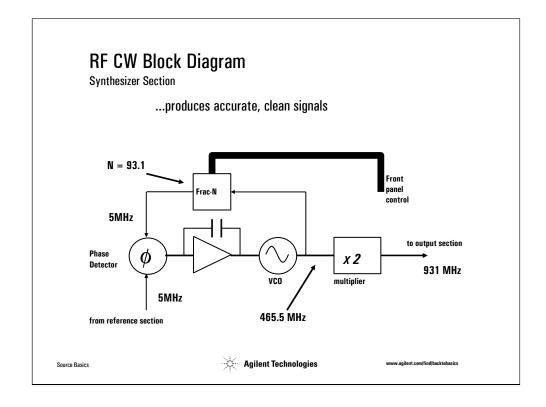


The heart of the reference section is the reference oscillator. The reference oscillator must be inexpensive, extremely stable and adjustable over a narrow range of frequencies. A stable reference oscillator will ensure that the frequency output of the source remains accurate in between calibrations. By comparing the reference oscillator to a frequency standard, such as a Cesium oscillator, and adjusting as needed, the source can be calibrated with an output that is traceable.

Of all materials today, crystalline quartz best meets these criteria. The fundamental frequency of quartz is affected by several parameters: aging, temperature, and line voltage. Over time, the stress placed on a quartz crystal will affect the oscillation frequency. Temperature changes cause changes in the crystal structure which affect the oscillation frequency. The piezoelectric nature of quartz is also affected by the electric fields created inside the source by the line voltage.

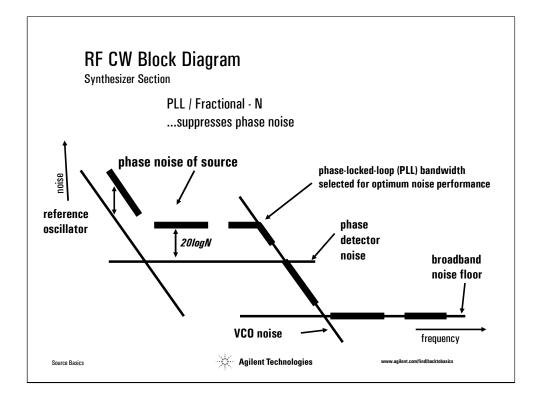
To improve the performance of quartz, temperature compensation circuitry is used to limit the variations in output frequency that result from variations in the operating temperature. Crystals with such compensation are referred to as Temeprature Compensated crystal oscillators or TCXO's. OCXO's are crystals that have been placed in an Oven Controlled environment. This environment maintains a constant temperature and provides shielding from the effects of line voltage. The stability for both TCXO's and OCXO's is tabulated above.

Many sources provide an external input that may be used to lock the oscillator to an external reference. The source, however, does not require an external reference.



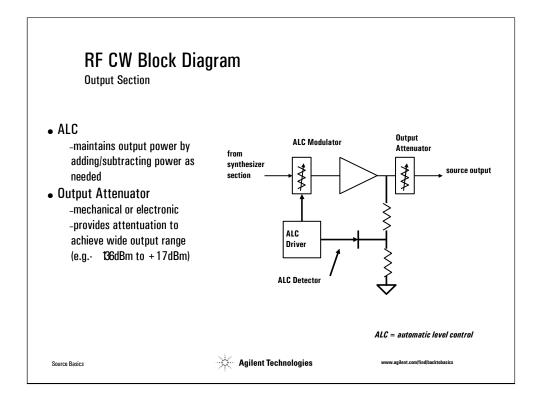
A VCO produces an output frequency for an input voltage. A simple VCO can be constructed from a varactor, a voltage-variable capacitor. A reverse-biased pn junction diode is a common type of varactor. The capacitance across a diode decreases as the reverse bias to the diode increases. When placed in an oscillator circuit, the tunable capacitor enables the output oscillation to be tuned. This output is inherently unstable. A PLL is required to maintain frequency stability.

Most of the VCO output is sent to the output section of the source. A portion of the VCO output is divided to a lower frequency. In the example above, the VCO output at 465.5 MHz is divided by 93.1 to produce a frequency of 5 MHz. This signal is compared to the 5 MHz signal supplied by the reference section. The output of the phase detector will be a dc offset with an error signal. The dc offset represents the constant phase difference between the 5 MHz signal from the reference and the 5 MHz signal from the Frac-N divide circuit. The error signal represents unwanted frequency drift. The output of the phase detector is filtered and amplified to properly drive the VCO. If the VCO does not drift, there will be (almost) no error signal at the output of the phase detector and the control voltage to the VCO will not change. If the VCO drifts upwards (or downwards), the error signal at the output of the phase detector will adjust the VCO output downwards (or upwards) to maintain a stable frequency output.



The synthesizer section of a source has a tremendous impact on the overall phase noise of the source. There are four main contributors to phase noise: The reference oscillator, the phase detector, the VCO, and the broadband noise floor. The broadband noise floor results primarily from the thermal noise present in the source. In general, this noise does not greatly limit the performance of the source. The phase noise of the reference oscillator and the VCO both fall off initially as 1/f³ and transitions to a 1/f² dependence. On a log-log plot, 1/f² translates to a slope of 20 dB per decade. The phase noise contribution of the phase detector is dominated by thermal noise and hence exhibits the same spectral dependency (or lack of spectral dependency) as the broadband noise floor. In addition, the Frac-N divide in the PLL degrades the phase noise performance by 20logN where N is the divide by number.

The bandwidth of the PLL determines the point at which the VCO contribution to the overall phase noise becomes supressed. For frequency offsets inside the PLL bandwidth, the overal phase noise of the source is dependent mainly upon contributions from the phase detector and the reference oscillator.

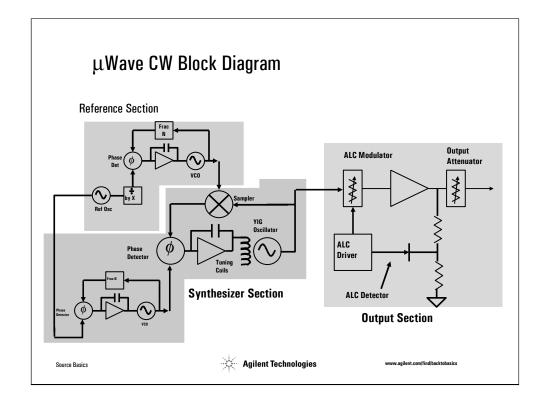


The output section maintains amplitude or level accuracy by measuring the output power and compensating for deviations from the set power level. The ALC driver digitizes the detector output and compares the digitized signal to a look-up table. The appropriate modulator drive is generated such that the detected power becomes equivalent to the desired power. Frequently, external losses from cabling and switching between the output of the signal source and the device under test (DUT) attenuate the signal. A look-up table that compensates for external losses can be input to extend the automatic leveling to the input of the DUT.

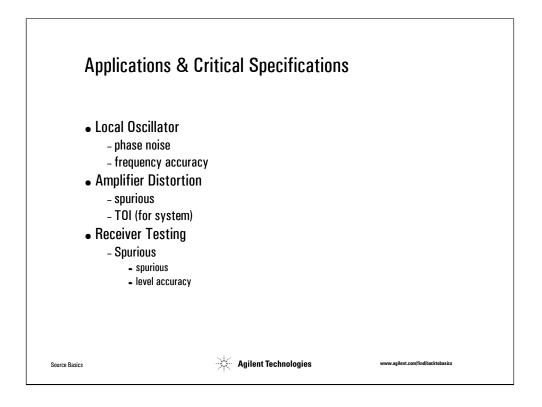
With no output attenuation applied, the source amplitude is at a maximum. The maximum amplitude is determined by the power amp and the loss between the output of the amp and the output connector. The main source of loss is the output attenuator. The output attenuator will introduce a finite amount of loss even when the attenuation is set to 0 dB. The purpose of the output attenuator is to reduce the output power in a calibrated and repeatable fashion. Today attenuators are available that provide output ranges from + 17 dBm (no attenuation applied to the source) to -136 dBm (maximum attenuation applied). There are two types of attenuators that are commonly used: mechanical and solid state.

Mechanical attenuators introduce very little loss between the output of the power amp and the output connector. Thus a high output power can be achieved without over-driving the output amplifier. Operating at low drive levels reduces the level of harmonics generated by the source. Mechanical attenuators do, however, have finite lifetimes. A typical mechanical attenuator will live for five million cycles. For an ATE application in which the power level is changed every two seconds, the attenuator will fail after about a year.

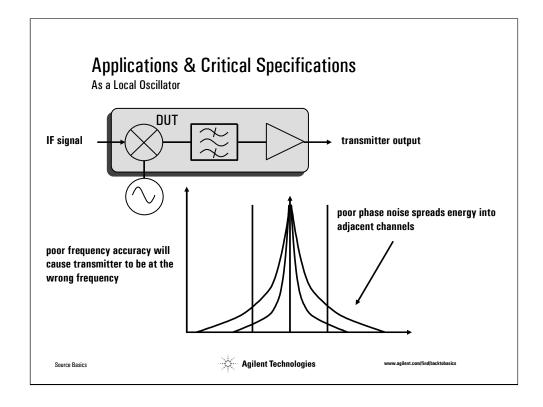
Solid state or electronic attenuators have essentially infinite lifetimes. For ATE applications, solid state attenuators are well suited. Solid state attenuators do introduce significant loss even when no attenuation is desired. Higher output amplifier drive levels are required in sources with solid state attenuators to overcome the losses. The higher drive levels increase the level of the harmonics. Sources with solid state attenuators, therefore, require more sophisticated designs to maintain an equivalent level of spectral purity with sources that use mechanical attenuators.



The block diagram of a microwave CW source is similar to that of an RF CW source; each has the same three basic sections. There are differences, however. Although the reference section only has one reference oscillator, two signals are supplied to the synthesizer section from the reference section. The output frequency of the synthesizer section is generated from a Yttrium-iron-garnet (YIG) oscillator which is tuned with a magnetic field. The feedback mechanism that ensures frequency stability is a phase locked loop; however, instead of a fractional-N divide, harmonic sampling is used to divide the output frequency.



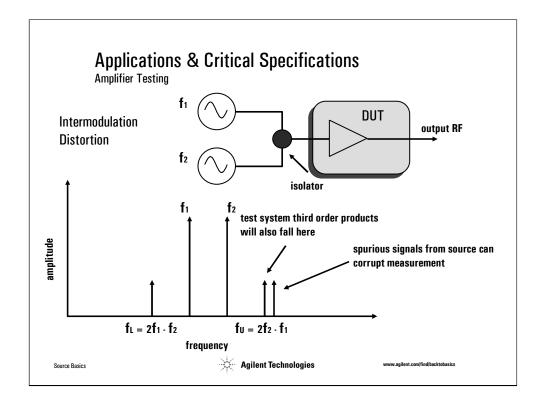
There are many, many applications for RF and microwave CW sources. The list above represents only a portion of the more common applications.



CW sources are often used as local oscillators in the development of transmitters and receivers.

Frequently during development, hardware sections of a prototype become available in stages. CW sources are often used in place of unfinished sections. For example, in the development of transmitter, if all sections except the local oscillator section are finished, a CW source is often used as the local oscillator.

When using a CW source as a local oscillator, phase noise and frequency accuracy are critical. Poor frequency accuracy will, for example, cause a transmitter to transmit at the wrong frequency. In a channelized communication system, poor phase noise will spread energy into adjacent channels. This spread into adjacent channels could be incorrectly attributed to the power amps of a transmitter.



Third order intercept, or TOI, is a common amplifier measurement. In this measurement, two CW sources are combined at the input of an amplifier. The frequencies of each source are slightly offset from each other and yet still inside the bandwidth of the amplifier. The non-linearities of an amplifier will produce third order mixing products:

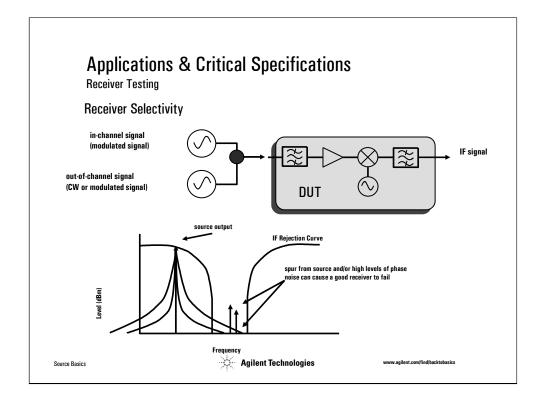
$$f_{L} = 2f_{1} \cdot f_{2}$$
$$f_{U} = 2f_{2} \cdot f_{1}$$

where f_1 and f_2 are the output frequencies of the two sources.

Spurious signals from the CW sources can corrupt the measurement. When selecting an appropriate source, the non-harmonic spurious levels should be well below the third order products produced by the amplifier under test.

The test system can also introduce sources of error. Whenever two signals are input to a combiner, the nonlinearities of the sources will create intermodulation products. The intermodulation products, when using a simple combiner, are created by the ALC of the source. The signal from the first source passes through the resistive combiner network and into the second source output with a 6 dB loss and the loss associated with the output attenuation of the second source. Because the two sources are at different frequencies, the sum of the two signals has an AM component equal to the difference frequency. For difference frequencies that are within the bandwidth of the ALC, the ALC of the second source sees this additional power and tries to level the output by adding AM. The intermodulation products created by the test system are at the same frequencies as those created by the amplifier under test.

Intermodulation products can be reduced either through better isolation of the signal sources or by suppressing the power that transfers from one source to the other.

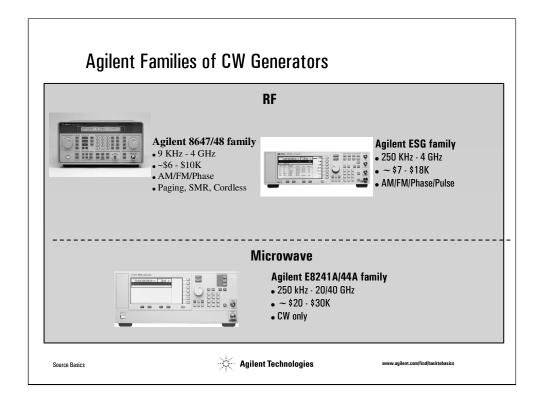


Spurious immunity is a measure of the ability of a receiver to prevent unwanted signals from causing an unwanted response at the output of the receiver. To make this measurement, one source inputs a modulated test signal at the desired channel frequency at a level above the sensitivity of the receiver. The second source outputs an interfering signal over a broad range of frequencies. The interfering signal may be modulated or unmodulated depending upon the frequency range and the communication standard. The output amplitude of the interfering signal is adjusted until the BER (for digital systems) or SINAD (for analog systems) of the receiver under test is degraded to a specified level. The difference between the test signal and the interfering signal is the spurious immunity of the receiver:

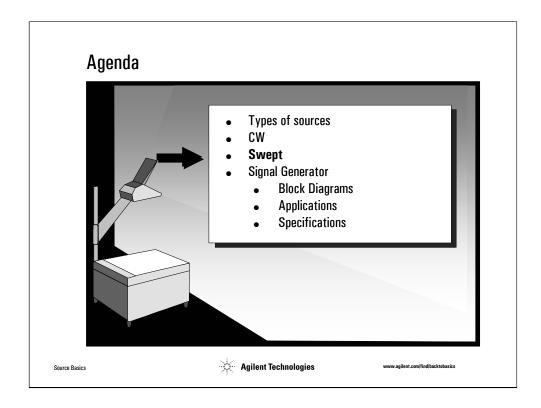
$$a_{spur} = P_{interferer} \cdot P_{test}$$

The non-harmonic spurious output of the interfering source must be at sufficiently low levels to ensure that the measurement is not affected. The non-harmonic spurious signals should be about 15 dB below the spurious immunity specification. At this level, spurs from the source will make only a minimal contribution to the overall inchannel noise floor.

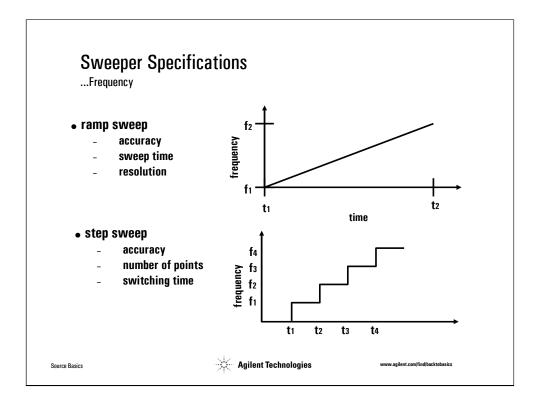
The level accuracy also effects the test. An example will illustrate how. If the set level of the interferer is OdBm and the set level of the test signal is -50dBm then the spurious immunity is 50dB. If the level accuracy of the two sources is +/-1dB, then the level of the interferer might actually be -1dBm and the level of the test signal might actually be -49dBm. This results in an actual spurious immunity of 48dB; not quite as good. By considering the level accuracy of the sources, an uncertainty for the measurement can be determined. In this case, the measured spurious immunity is 50dB + /-2dB. The uncertainty is *twice* the level accuracy.



Shown here is a summary of Agilent's family of CW generators.

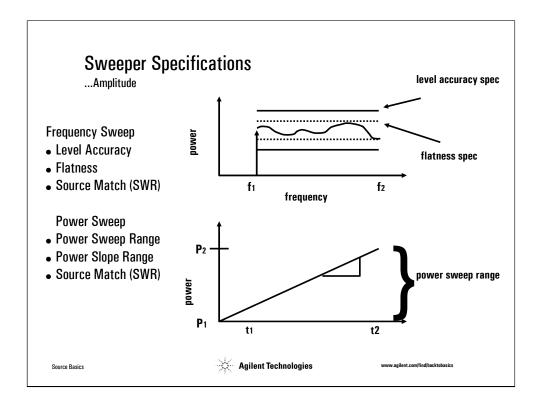


Slide 20



Sweepers add the ability to sweep frequency, power, or both. There are two types of frequency sweeps: ramp sweep and step (or arbitrary list) sweep. In ramp sweep, the output sine wave frequency is increased from a start frequency to a stop frequency. This produces a linear frequency versus time plot. In step (or list) sweep, the output frequency is abruptly changed from one frequency to another. The source will then remain at each new frequency for a specified length of time.

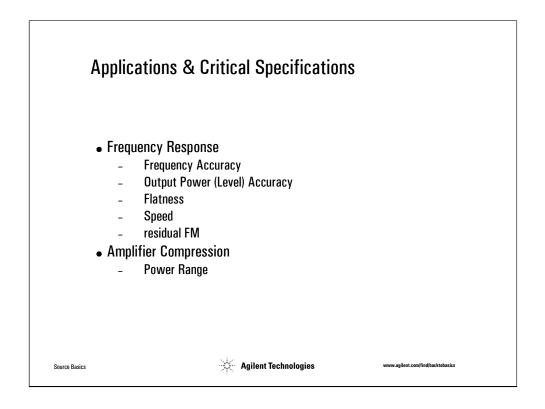
For ramp sweep, the accuracy, sweep time, and frequency resolution of the source are usually specified. For step sweep, the accuracy, number of points, and switching time are specified. The number of points may be as few as two or as many as several hundred. The switching time is the time needed by the source to switch from one frequency to another.



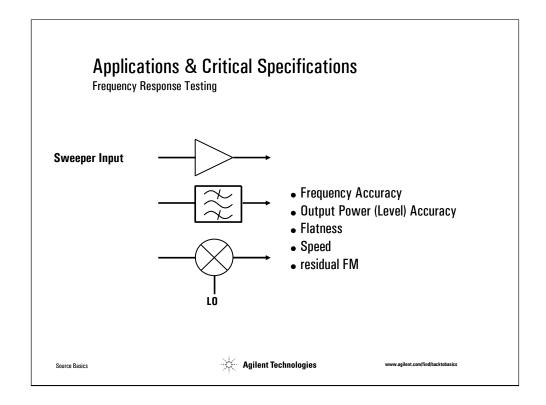
The output power will vary by no more than the flatness specification throughout the sweep. In addition, the output power is also constrained to remain within the level accuracy specification of the source. For example, consider a source with a level accuracy of +/- 1.0 dB and a flatness specification of +/- 0.7 dB. If the output is set to 0 dBm, the actual output could really be as high a 1 dBm or as low as -1 dBm. If the actual output is 1 dBm, during the sweep, the power can only drift downward by the 0.7 dB, the flatness specification; the power cannot drift above 1 dBm because the ALC will constrain the power to remain within 1 dB of the set level of 0 dBm.

When sweeping power, the sweep range will determine possible range of output powers. The slope range will determine how quickly the source can sweep from one power to another. In place of a power slope, some sources allow the user to specify the number of points in the power sweep and the dwell time.

Source match is generally specified in standing wave ratio (SWR); SWR is really just a measure of how close the source output is to 50ohms. The value of SWR can range between one and infinity. One is a perfect 50ohm match and infinity is, well, really REALLY bad. If the output of the source is not exactly 50ohms, the SWR value will be greater than one. Some of the power from a source with a SWR greater than one, when connected to a 50ohm load, will be reflected back to the source.



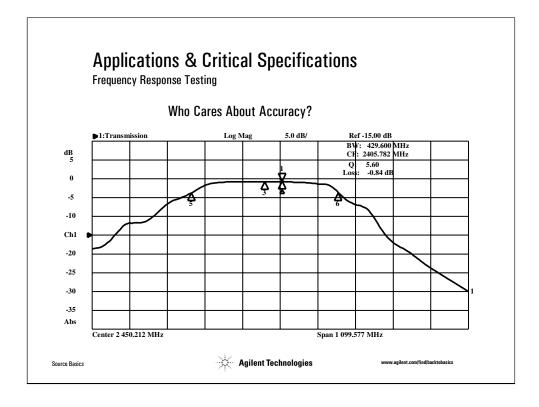
Frequency sweeps are done to determine the frequency response of devices. Power sweeps, typically done on amplifiers, measure saturation levels.



When measuring the frequency response of a device, the following sweeper specifications are important:

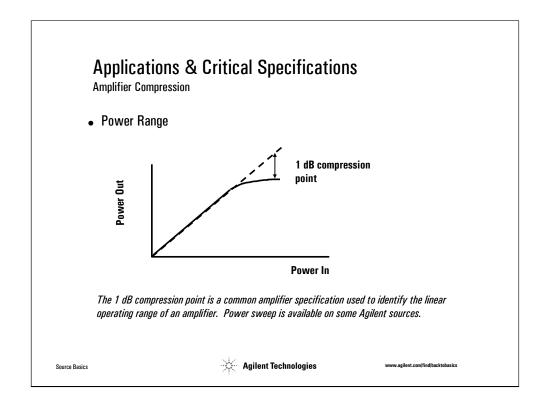
Specification	Effect
Frequency Accuracy	center frequency of device under test (DUT)
Output Power (Level)	gain or loss
Flatness	flatness
Speed	test cost
residual FM	ability to test high Q devices

Frequency response measurements are made on many types of devices.



Who cares about frequency accuracy? If you're making filters whose 3 dB roll off frequency is better than your competitors, you'd better be able to measure that frequency accurately. A source testing a filter operating near 1 GHz can only set frequency to +/- 10 Hz if the frequency accuracy is 0.01 ppm. Is this accuracy 0.01 ppm enough? Ask your customer: It really depends on the accuracy requirements for parameters such as 3dB bandwidth and gain.

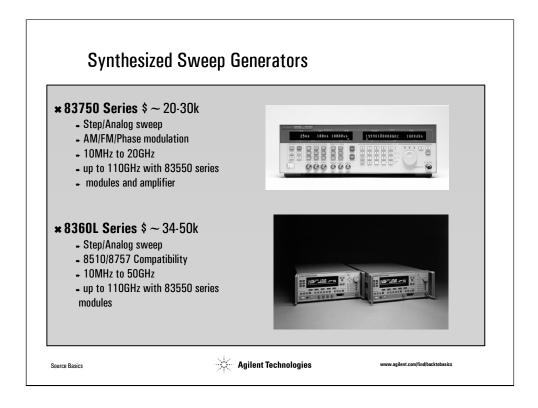
Most channelized frequency communications system employ band pass filters. A frequency inaccuracy can lead to an amplitude measurement error due to the shape of the filter.



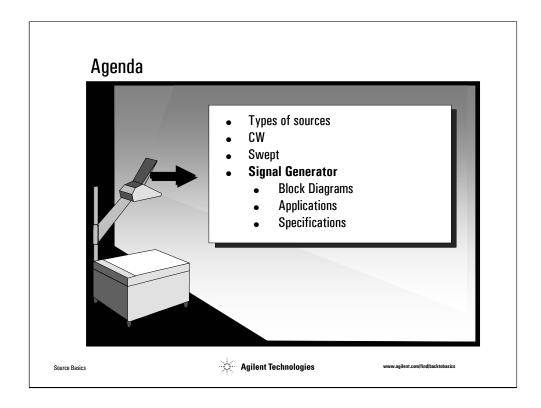
Power sweeps are commonly done on amplifiers to determine 1 dB compression points. A wide power range is needed to drive the amplifier into compression. What cause compression? Consider (again) the output of an amplifier with an input sinewave:

 $v_0(t) = a_1 \sin(\omega t) + a_2 \sin^2(\omega t) + a_3 \sin^3(\omega t) + \dots$ = $a_2/2 + a_1 \sin(\omega t) + 3a_3/4 \sin(\omega t) + a_2/2 \sin(2\omega t) + a_3/4 \sin(3\omega t) + \dots$

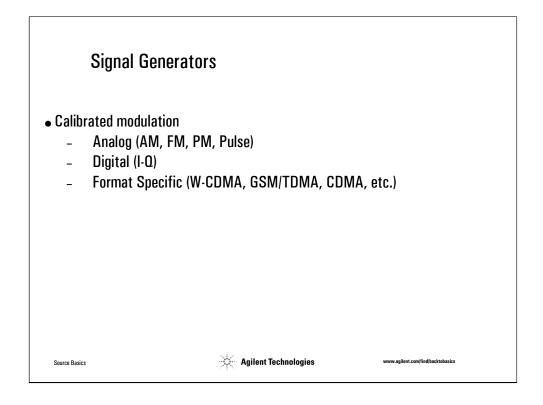
When the output no longer tracks the input the amplifier begins to go into saturation. With a high enough input level, the gain of the amplifier is decreased by 1 dB. Where has the power gone? When an amplifier becomes saturated, the output power shifts to the harmonics and heat.



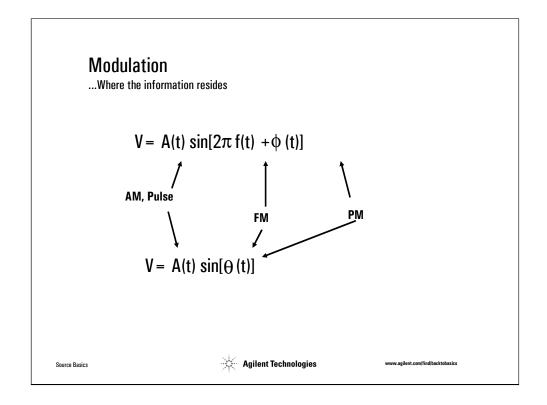
Shown here is a summary of Agilent's family of Synthesized Sweep generators.



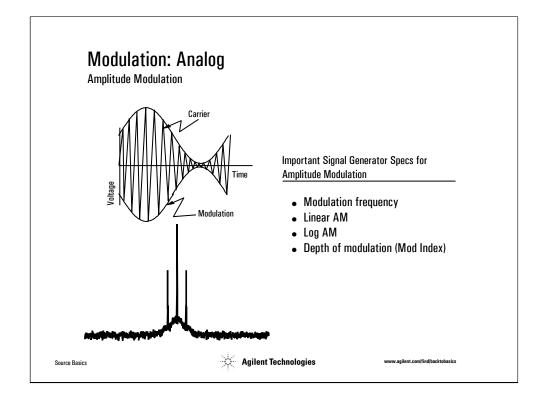
Slide 28



A basic signal generator is a source whose output frequency and output level (amplitude) are variable over a wide range and are always known. A signal generator must also have calibrated modulation. The ability to generate modulated signals is the main difference between a signal generator and a CW source.



Consider the basic equation of a sine wave. There are three parameters that can be varied: Amplitude, frequency, and phase. Amplitude and pulse modulation are achieved by varying the amplitude of a sine wave. Varying the frequency or phase of the sine wave generates FM and PM. Both FM and PM vary the angle of the sine wave, when viewed in polar coordinates, and may be referred to more generally as angle modulation.



In amplitude modulation, the modulating signal varies the amplitude of the carrier. The modulating signal carries the information. Amplitude modulation can be represented by the equation:

 $s(t) = A_c \sin(2\pi f_c t) [1 + k(t)]$

where *fc* is the carrier and k(t) is the modulation.

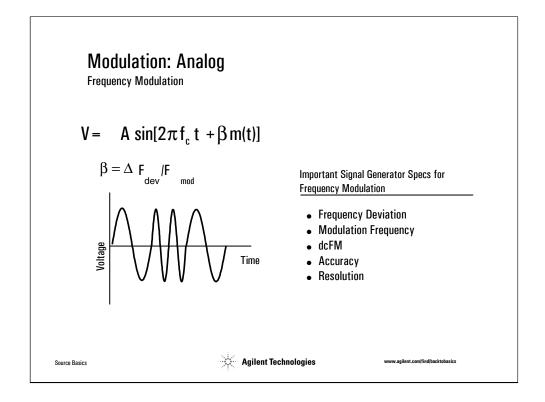
Most text book analyses of modulation assume the k(t) modulating signal is a sine wave and, remembering that any waveform may be represented by a sum of sine waves, leaves the more complicated analysis to the student.

If $k(t) = msin(2\pi f_m t)$, then:

$$s(t) = A_c sin(2\pi f_c t) [1 + m sin(2\pi f_m t)]$$

This is the classic equation for AM where m is the depth of modulation, also referred to as the modulation index, and *fm* is the modulation frequency. The depth of modulation is defined as the ratio of the peak of the modulating signal to the peak of the carrier signal. When the depth of modulation is expressed as a percentage, the modulation is referred to as linear AM. When the depth of modulation is expressed in "dB", the modulation is referred to as logarithmic AM.

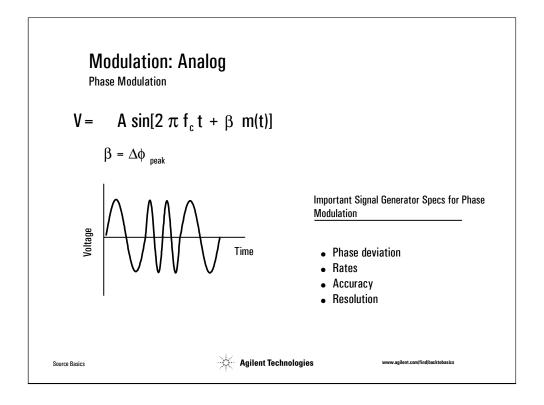
The spectrum of an AM signal contains several sidebands. These sidebands are created from the sums and differences of the carrier frequency and the modulation frequency.



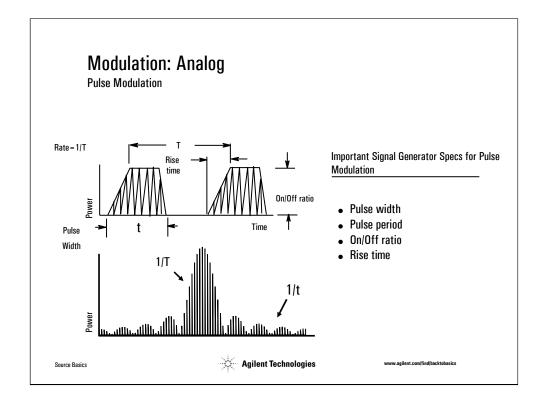
In frequency modulation, the modulating signal changes the frequency of the carrier. The amplitude of the modulating signal determines how far (in frequency) the carrier signal will shift; this is referred to as the frequency deviation or $\Delta F dev$. The frequency of the modulating signal determines how quickly the carrier will shift from one frequency to another; this is referred to as the modulation frequency of Fm.

For FM, the math gets more complicated. For a given frequency deviation and a given rate of frequency change, the modulation index, called β , is defined as $\Delta Fdev|Fm$.

Frequency modulation, depending on the modulation index, can create an infinite number of sidebands around the carrier. A mathematical solution to frequency modulation requires Bessell functions. The Bessell functions provide an indication of the number and relative strength of the sidebands. The interesting thing about FM is that, with the proper modulation index, the carrier can completely disappear. We will see how this is done later.

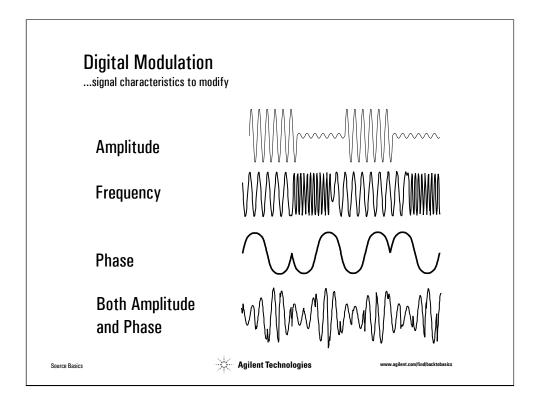


Phase modulation is very similar to frequency modulation. The modulating signal causes the phase of the carrier to shift. The amplitude of the modulating signal determines the phase deviation. The modulation index, β , is defined as the phase deviation of the carrier. Notice that the rate of the phase modulation does not enter into a calculation of β . The spectrum modulation components are spaced as with FM and are determined by the rate of phase modulation, but β will not change if the rate of phase modulation is varied. If β doesn't change, the shape of the spectrum doesn't change: only the component spacing changes. This is really the only way of differentiating analog FM from analog PM.



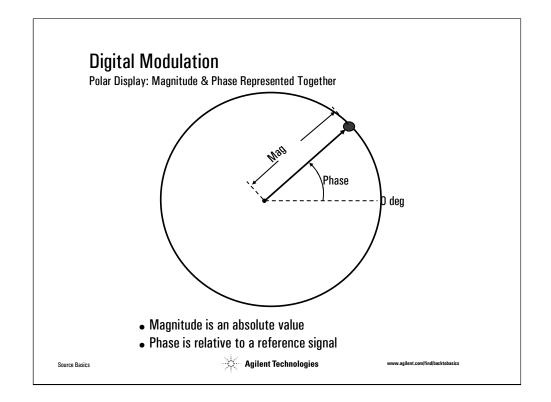
Pulse modulation is important in both comms and radar applications. In comms, the baseband signal is essentially a pulse and the upconverted signal may be time multiplexed (turned on and off rapidly). A variety of comms, satellite, and radar signals can be generated using a combination of pulse modulation and either FM or PM.

The most important parameters for pulsed RF signals are the pulse rise and fall times, pulse repitition frequency (PRF), pulse period, and pulse width. The line spacings in a pulsed spectrum are separated by the reciprocal of the pulse period. The nulls occur at 1/t where t is the pulse width. The overall shape is a sin(x)/x.

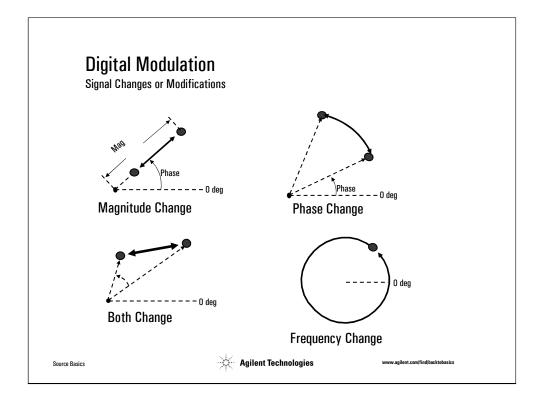


The only difference between analog (old-fashioned) modulation and digital (new-fangled) modulation is that digital modulation restricts the modulating baseband signal to discrete states rather than allowing the modulating signal to take on any value between a maximum and a minimum value.

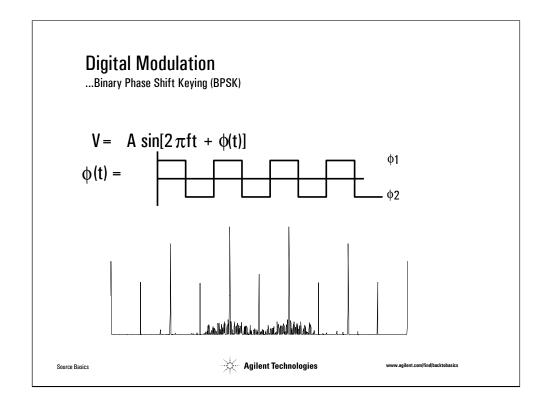
When AM, FM or PM are used in a digital modulation scheme the names become ASK, FSK and PSK. The SK stands for shift keying and is derived from the telegraph key. The modern use implies shifting between discrete states.



The signal vector, as represented in the IQ plane, is a phasor. The phasor notation provides a convenient way of measuring how the sine wave is changing over time. The phasor doesn't easily provide any frequency information. The rotation of the phasor is referenced to the carrier frequency, therefore the phasor will only rotate if its frequency is different from the carrier frequency.



As mentioned earlier, phasor notation can be used to represent all types of modulation. Amplitude modulation is represented by a magnitude change with no rotation. Phase modulation is represented by a phasor that moves along an arc; the length of the arc indicates the maximum phase deviation. Simultaneous amplitude and phase modulation is indicated by a phasor whose length and phase change with time. Frequency modulation results in a phasor that rotates clockwise or counterclockwise.

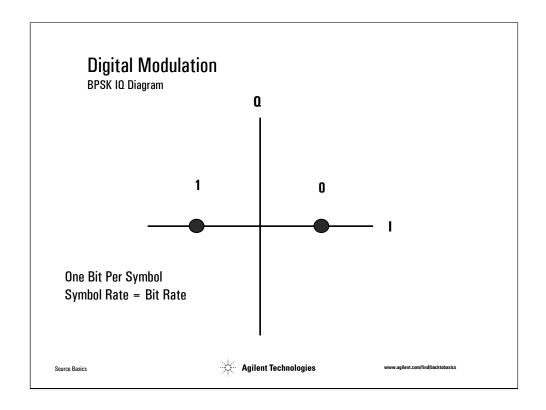


In phase shift keying, the phase of the carrier signal is shifted between discrete states. There are two common types: Binary phase shift keying (BPSK) and quadrature phase shift keying (QPSK).

BPSK is generated by varying the phase of the carrier between two states that are normally separated by p radians (180 degrees). Let's examine some of the basic properties of BPSK.

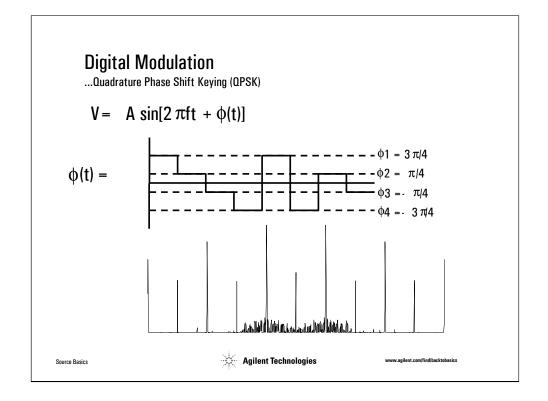
BPSK can be achieved by phase modulating a carrier with a square wave. The square wave will force the carrier to change phase between two phase states. Using a square wave causes a very abrupt transition; this creates a very wide spectrum. Most BPSK modulators employ some type of filtering that causes the phase transitions to be less abrupt - this reduces the occupied spectrum of the signal. The BPSK spectrum reflects the discrete nature of the modulation.

Lets look at the I - Q diagram of BPSK..



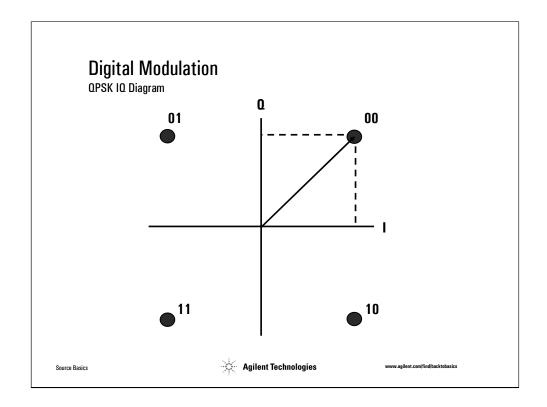
On an I and Q diagram, the I state has two different values. There are two possible locations in the state diagram, so a binary one or zero can be sent. The symbol rate is one bit per symbol. BPSK is one of the simplest forms of digital modulation, and is used for deep space telemetry.

Let's look at a slightly more complicated form of phase shift keying, QPSK.



In a QPSK signal, the phase of the carrier is varied between one of four different phase states. These states are normally separated by $\pi/2$ radians. A QPSK signal may be generated by phase modulation with a modulating waveform that contains four discrete levels.

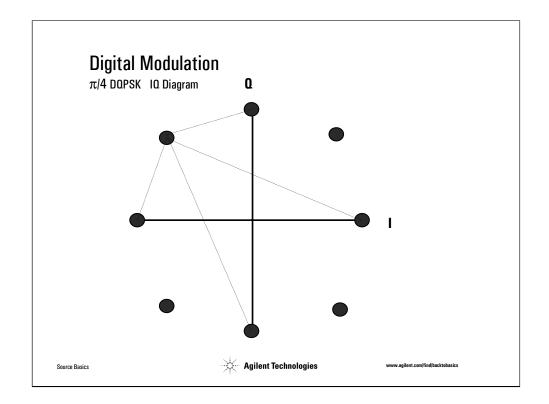
The output spectrum of a QPSK signal is similar to that of a BPSK signal.



Because they are orthogonal signals, the I and Q signals may be mapped onto a set of orthogonal axes: The IQ plane. A constellation diagram indicates the allowable states. For QPSK, there are four allowable states defined by the set of four IQ points:

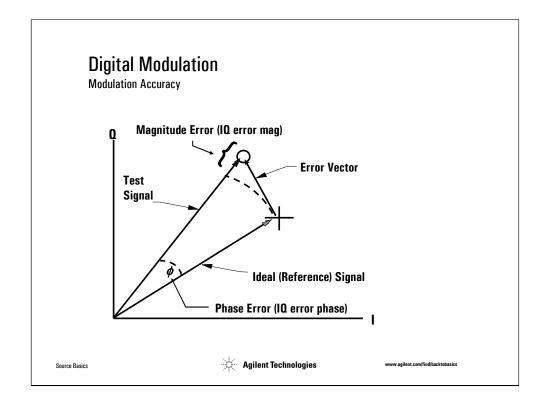
10:

The signal at each of these states may be represented by a vector drawn from the origin to the allowable state. The length of the vector indicates the magnitude (power) of the signal. The rotation off of the I axis indicates the phase of the signal (relative to the carrier). The diagram above indicates the position of the signal at one point in time. Over time the vector will rotate from one state to another.



NADC Constellation

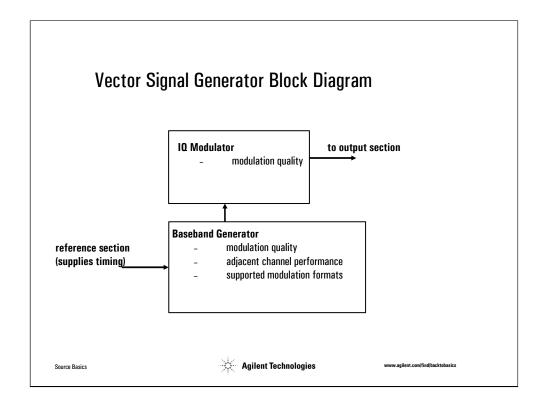
pi/4 DQPSK is differential method used in NADC handsets, so power amp does not turn off.



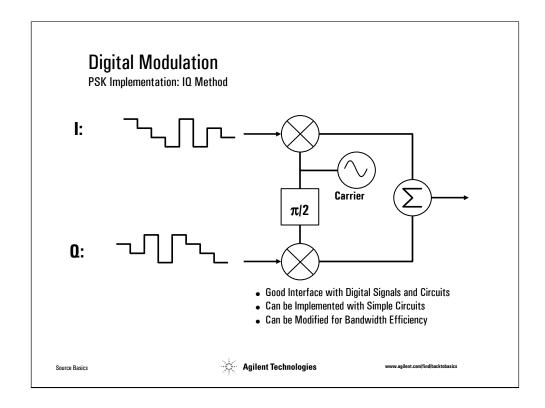
The IQ constellation of our digitally modulated signal provides a wealth of information. Recall first the basics of digital modulation: Digital bits are transferred onto an RF carrier by varying the carrier's magnitude and phase such that, at each data clock transition, the carrier occupies any one of several unique phase and amplitude locations on the IQ plane. Each location encodes a specific data symbol, which consists of one or more data bits. A constellation diagram shows the valid locations at the decision time (i.e., the magnitude and phase relative to the carrier) for all permitted symbols, of which there must be 2ⁿ, given *n* bits transmitted per symbol. Thus, to demodulate the incoming data, one must accurately determine the exact magnitude and phase of the received signal for each clock transition.

At any moment in time, the signal's magnitude and phase can be measured. These values define the actual or "measured" phasor. At the same time, a corresponding ideal or "reference" phasor can be calculated, given knowledge of the transmitted data stream, the symbol clock timing, baseband filtering parameters, etc. The differences between these two phasors provides both the signal error vector magnitude (EVM) and the phase error. By convention, EVM is reported as a percentage of the ideal peak signal level, usually defined by the constellation's corner states.

EVM and phase error are the two principal parameters for evaluating the quality of a digitally modulated signal. A typical source EVM is around one percent.



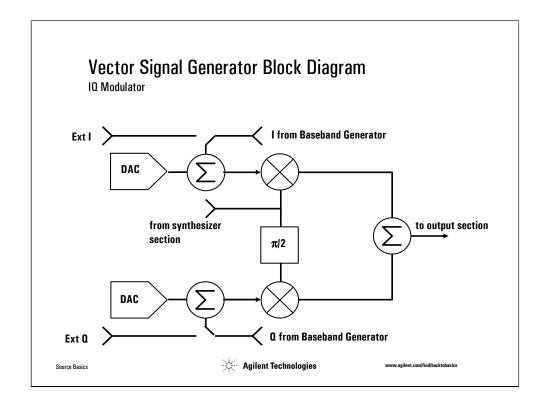
A vector signal generator is created by adding two new blocks to the basic block diagram of a signal generator: an IQ modulator and a baseband generator.



Expressing the output signal as the sum of in-phase and quadrature components leads to a natural hardware implementation commonly known as IQ modulation. IQ modulators can be implemented with simple circuits. By modifying the baseband inputs to an IQ modulator, high bandwidth efficiency can be achieved.

IQ modulation is well suited for generating digital signals but may also be used to create traditional AM, FM, and PM signals. When generating a QPSK signal, controlling two voltage states for the I and Q inputs may be done more accurately than changing the phase directly between four different phase states.

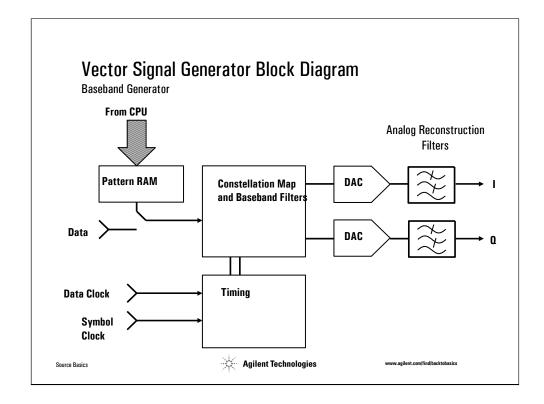
Most modern transmitters employ IQ modulation for the generation of digital signals. IQ modulators interface well with digital circuits (e.g. DAC's, DSP processors).



The baseband information for the IQ modulator section can come from two paths: the internal baseband generator or the external I and Q inputs. The information is summed with calibration factors that are stored in ROM look-up tables and are output by a pair of DAC's. This enables the modulator to provide a calibrated, high quality output over a broad range of frequencies.

Today most wireless communications transmitters use an IQ modulator. External I and Q inputs enable users to create custom signals or to test their own baseband generators. When using external sources for I and Q, the input drive level is important. Most IQ modulators have an optimum drive level for maximizing the output signal quality:

For I and Q waveforms that have large peak to average ratios, the input drive level needs to be reduced below the optimum level. This results from the fact that at large peak to average ratios, the peak signals can cause a significant amount of spectral regrowth at the output of the signal generator.



The baseband generator creates the baseband waveforms needed to drive the IQ modulator. The above block diagram provides three paths for supplying data for the baseband waveforms:

Data may be loaded from an external computer Data may be loaded directly from RAM TTL data may be input (this requires both a data clock and symbol clock)

The data is the raw "1's" and "0's" that will be used to construct the baseband signal. Data bits are combined to make symbols for modulation formats that require more than one bit per symbol. Filtering is added to increase the bandwidth efficiency of the output signal. The filtering is done digitally. The digital stream is sent to a DAC. The output of the DAC's are sent to analog reconstruction filters. These filters are smoothing filters that remove the high frequency components of the waveforms that cause spectral spreading:

	ctor Signal Generato nat Specific Digital Signals		
Γ	NADC (TDMA IS-54)		
F	Parameter	Specification	
	Access Method	TDMA/FDD	
F	Modulation	π/4 DQPSK	
	Channel Bandwidth	30 kHz	
	Reverse Channel Frequency Band	824- 849 MHz	
	Forward Channel Frequency Band	869- 894 MHz	
	Filtering	0.35 RRC	

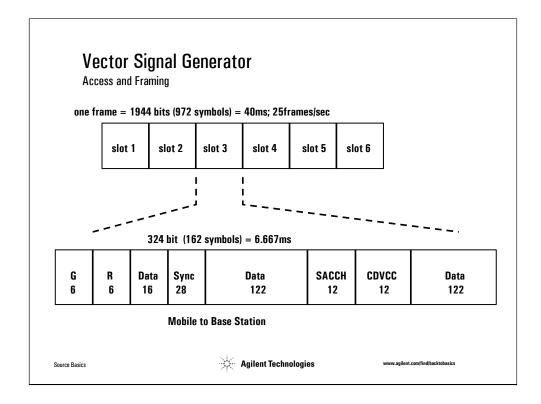
The table above illustrates the types of parameters that are specified for digital formats.

The combination of the baseband generator and the IQ modulator produce a digitally modulated signal. The filtering and modulation type are determined by the shape of the baseband waveforms.

To accurately simulate a digital modulated signal, however, the signal generator must do more than just output the proper modulation. Most digital communication formats, in an effort to conserve bandwidth, have some access scheme. For US-TDMA (IS-54), the access scheme requires a separation in frequency between the forward, base to mobile, and reverse, mobile to base channels. In addition, the forward and reverse links are each allocated a specific slice of time during which communication takes place: This is called Time Division Multiple Access or TDMA. This "slice of time" is generally referred to as a time slot.

The following formats are commonly found in most vector signal generators:

GSM, DECT, Tetra, US-TDMA (NADC, USDC, or IS-54), PDC, PHS CDMA (IS-95), W-CDMA, cdma2000, 1xEV-D0, 802.11a/b



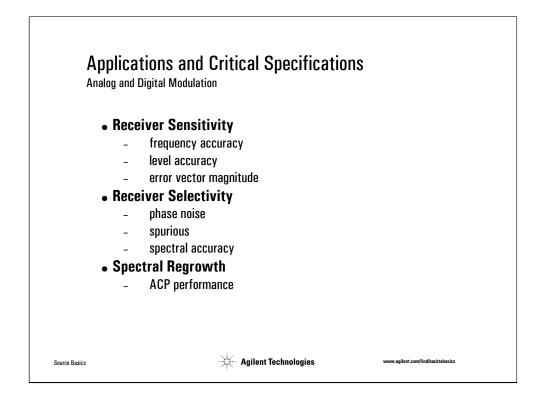
For US-TDMA, the time slot is part of a frame; there are six time slots per frame. GSM, another TDMA format, uses eight time slots per frame and combines frames into multiframes and superframes.

The bits in a timeslot are grouped to perform various functions. For example, in a US-TDMA system the SACCH and CDVCC are special groupings of bits:

CDVC C (Coded Digital Verification Color Code): Handshaking between base and mobile SACCH (Slow Associated Control Channel): Communicate power level changes, hand-off requests

The transmitted voice is contained in the data fields. During testing, standard and special bit patterns are placed in these data fields. Psuedo-random sequences, such as PN9 and PN15 sequences, are examples of standard bit patterns. Special sequences are generally defined by the user.

Signals that are representative of "real world" signals are needed to fully test receivers. Sophisticated signal generators provide the capability to produce signals that are properly modulated, emulate different access schemes (e.g TDMA), and incorporate some level of protocol.

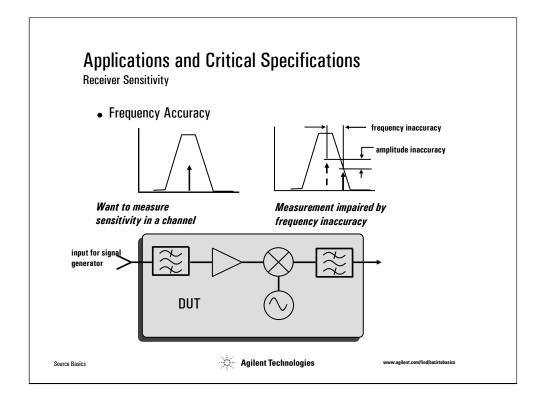


An entire seminar could be devoted to applications of signal generators. Signal generators are used to test receivers as well as the components in a receiver. Sensitivity and selectivity are two receiver tests that are required by most standards. In addition to these two, other common receiver tests include:

Co-channel immunity Noise figure Intermodulation rejection

Most standards include detailed descriptions of how these tests are performed. Spectral regrowth is a common transmitter and amplifier test.

When making any test, the specifications of the signal source must be analyzed to ensure that the source does not corrupt the measurement. The critical specifications that a source must meet vary depending upon the test.



The sensitivity of a receiver is the lowest possible signal level that can be reliably detected. Sensitivity is one of the key specifications for a receiver and is generally specified at a particular SINAD for FM receivers or BER for receivers of digitally modulated signals. For FM receivers, SINAD is a figure of merit used to describe the usable signal out of a receiver. SINAD is the ratio of the signal plus noise plus distortion to the noise plus distortion at the same output:

$$SINAD = 10 \log \left[(S + N + D)/(S + N) \right]$$

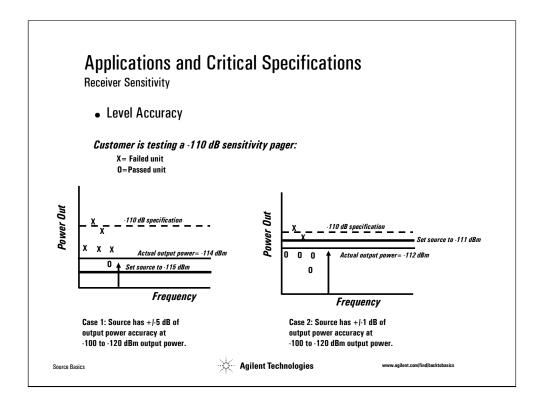
The level of RF input required to maintain a SINAD of 12 dB is generally defined as the sensitivity of the receiver because this level provides a good quality audio signal. For receivers of digitally modulated signals, sensitivity is defined as the level of the received signal that produces a specified BER when the signal is modulated with a specified psuedo-random binary sequence (PRBS) of data.

The following critical signal generator specifications for measuring the sensitivity of a receiver will be discussed:

frequency accuracy amplitude (level) accuracy error vector magnitude (for digitally modulated signals)

Frequency modulation deviation accuracy and frequency modulation distortion are two other specifications that affect sensitivity measurements.

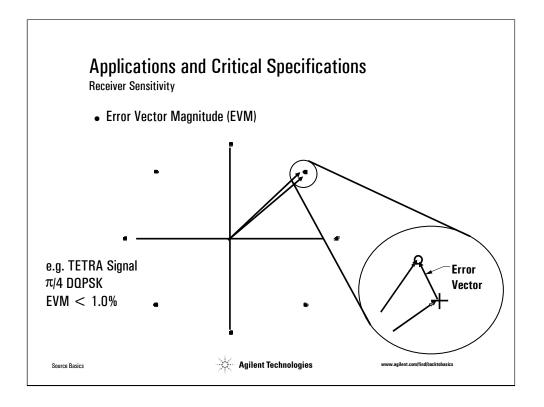
Poor frequency accuracy will cause the signal to fall nearer to the skirts of the filters in the receiver; this will degrade the level of the signal and will reduce either the SINAD or BER measurement. A receiver will appear to have a lower sensitivity when tested with a signal that has poor frequency accuracy.



When making a sensitivity measurement, the level accuracy of the signal generator is extremely important. For example, a pager receiver has a specified sensitivity level of -110 dBm. The measurement system will introduce error. The amplitude level accuracy of the signal generator supplying the test signal is the main source of error. In order to ensure that no receivers are passed with sensitivities that do not meet -110 dBm, the amplitude of the signal generator must be set below the receiver specification by an amount equal to the level accuracy of the signal generator. In this example, for a signal generator with a level accuracy of +/-5dB, the maximum amplitude of the test signal is set to -115 dBm.

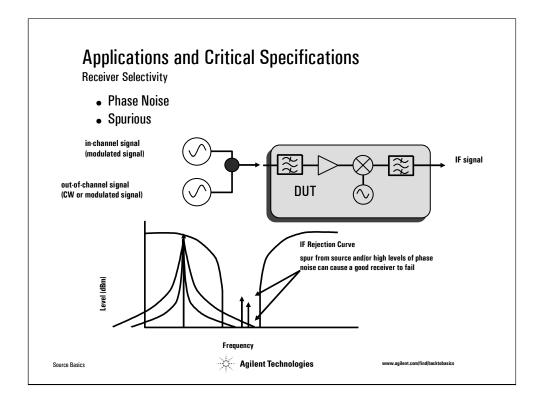
In this example, the maximum signal generator level of -115 dBm ensures that only good receivers pass. However, not all receivers that are good will pass. For example, with a level accuracy of +/-5dB at a nominal level of -115 dBm, the output of the signal generator may be as high as -110 dBm (the receiver spec) or as low as -120 dBm. A good receiver may not work at -120 dBm but, because of the signal generator uncertainty, may be tested at -120 dBm. Of the six pagers tested in this example, only one passed.

When tested with a signal generator that has a level accuracy of +/-1dB, the number of pagers that passed increases dramatically.



The best indicators of modulation quality are obtained from the constellation diagram of a signal. For phase shift keyed signals, the EVM measures the signal quality. For frequency shift keyed signals, the signal phase error is a more appropriate measurement. For amplitude shift keyed signals, magnitude error should be used.

For the above TETRA signal, the EVM is less than one percent. The size of the dots indicates the quality of the signal: A signal with a larger EVM would have larger dots.



Adjacent and alternate channel selectivity measures the receiver's ability to process a desired signal while rejecting a strong signal in an adjacent channel or alternate channel. This test is very important for communication receivers where channel spacings are narrow and many signals may be encountered in a small geographical area. An adjacent or alternate channel selectivity test setup is shown above. One signal generator inputs a test signal at the desired channel frequency at a level above the sensitivity of the receiver. The second signal generator outputs either the adjacent channel signal, offset by one channel spacing, or the alternate channel signal, offset by two channel spacings. The output of the out-of-channel signal is increased until the sensitivity is degraded to a specified level.

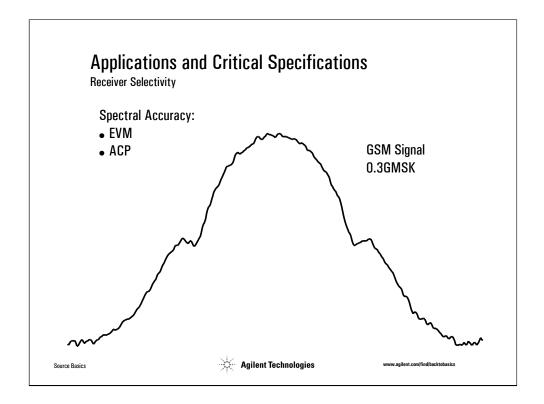
Frequency and amplitude (level) accuracy and the spectral characteristics of the test and interfering signal are important.

Poor frequency accuracy will cause the signals to be either too close or too far from each other and from the filter skirts. This can have the effect of appearing to improve or degrade the receiver performance.

We saw how level accuracy can affect the sensitivity measurement of a receiver. With two signals, the problems associated with inaccurate signals are compounded.

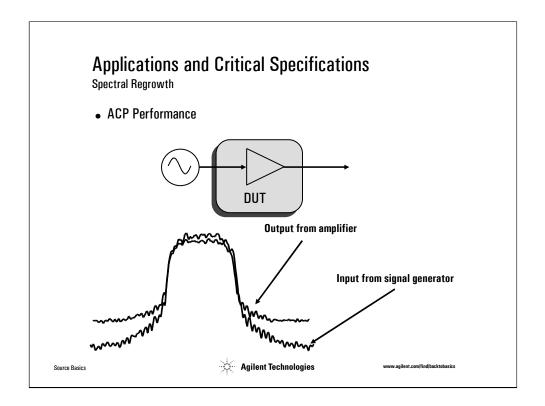
For FM receivers, the SSB phase noise of the interfering signal is the most critical spectral characteristic. The test is a measure of the performance of the receiver's IF filters. As the signal in the adjacent-channel is increased, the rejection of the IF filter outside the passband is eventually exceeded. If the phase noise energy inside the passband is detected, the receiver may appear to fail the test.

High levels of spurs can also degrade the selectivity measurement of a receiver. Signal generator spurs that fall within the passband of the receiver will contribute to the overall noise level in the passband.



When measuring selectivity on receivers designed for digital signals, the most important spectral characteristic is spectral accuracy. With digital signals, the modulation sidebands are often wider than the channel spacings. These sidebands have considerably higher power at adjacent and alternate channel offsets than analog FM signals. Because of this, the phase noise and the spurious of the signal generator is much less important.

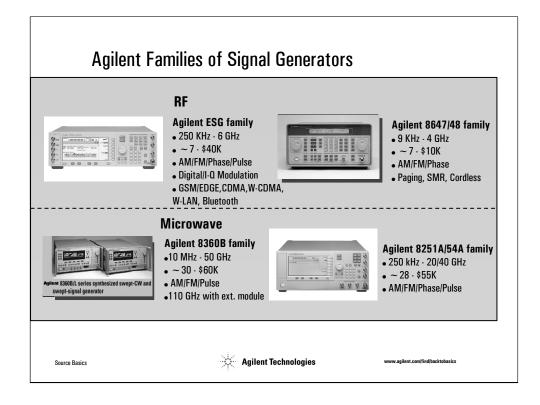
However, the spectral shape is very important. For the adjacent-channel interferer, the spectral shape should be exact. EVM is a good indicator of the spectral shape within the modulation bandwidth of a signal. However, even with a good EVM, a signal may have a significant amount of spectral splatter outside of the modulation bandwidth. Comparing the measured adjacent-channel power (ACP) to the theoretical ACP provides an indication of the spectral quality outside of the modulation bandwidth.



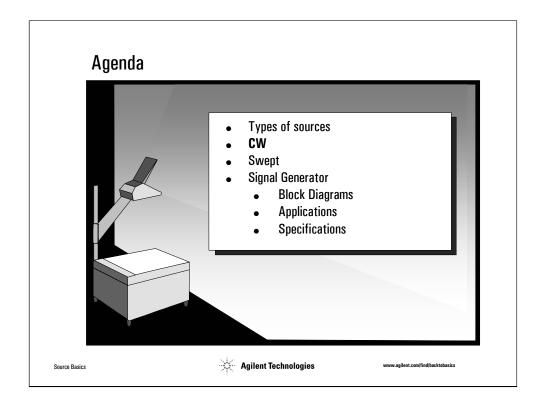
Spectral regrowth is a common amplifier test. When stimulated with a digitally modulated signal, the nonlinearities in amplifiers create shoulders in the output spectrum. These shoulders are referred to as spectral regrowth. Spectral regrowth is related to intermodulation distortion. Intermodulation distortion results from the interaction between two (or more) input sine waves. A digitally modulated signal can be expressed as an infinite sum of sine waves with properly weighted coefficients:

The interaction of these sine waves produces the spectral regrowth.

Signal generators have amplifiers that can also introduce spectral regrowth. When measuring an amplifier, the spectral regrowth, or ACP performance, of the signal generator should be less than that of the amplifier under test.



Shown here is a summary of Agilent's family of signal generators



This seminar reviewed the basics of sources. Aspects of the design, specification, and application of sources were explored. A brief list of some of the reference material has been included for further study. In addition, Agilent has an extensive library of application notes that provide more information on how to use sources.